ROTARY ENCODER

Absolute single-turn magnetic encoder with integrated inclinometer









ADVANTAGES

Measuring range up to 360°

High resistance to shock and vibrations

Compact size

High accuracy of measurement

High protection level and wide temperature range

Multi-variable position sensor (angle & inclination)

Detection of magnetic loss



Reliability and long service life in outdoor use

Optimized for integration in mobile machines

Several connection types available

Highly configurable via CANopen

Firmware upgradable via proprietary bootloader

Recommended for safety relevant applications



High protection level



Shock/vibration resistant



Functional safety



Reverse polarity protection



Wide temp. range



CANopen



CANopen Safety



Firmware Upgradable



High accuracy



RoHS compliant



UNECE R10 conformity



EU conformity

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RTS100 is a new generation of multi-variable position sensor by TSM.

It has a particularly compact and robust plastic housing that, in a diameter of just 50 mm, encloses the technological heart of the sensor, a system for simultaneously measuring of angle position an inclination based on Hall Effect and MEMS components.

The contactless technology make this sensor a very robust device with expected life practically infinite thanks to the absence of wear on the sensing element.

Excellent accuracy, high IP rating, shock and vibration resistance and electromagnetic immunity makes this transducer suitable for outdoor mobile hydraulic applications such as: agricultural vehicles, construction equipment, loader cranes, telehandler and aerial work platforms. Due CANopen safety protocol and SIL2-Pld certification it is recommended for safety relevant applications.









Agricultural machinery



Construction



Earth moving



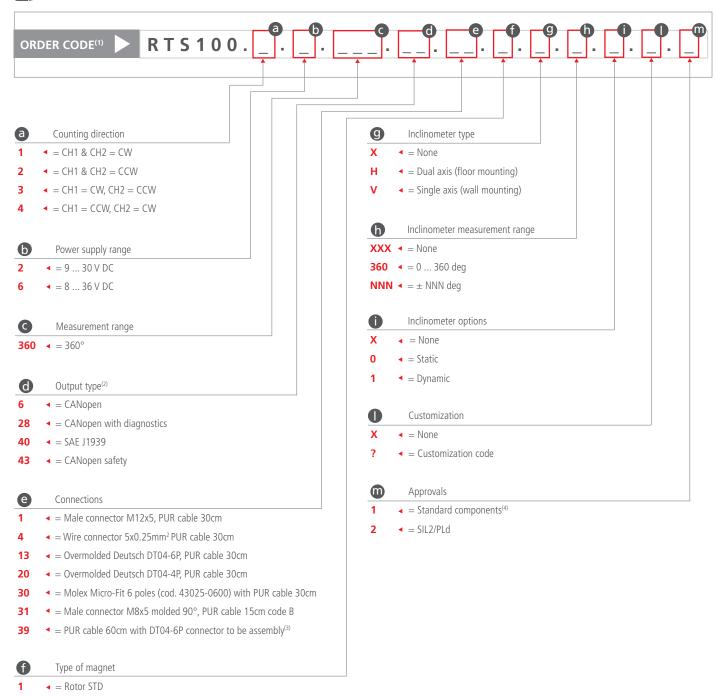
Handling and lifting

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- (1) Not all combinations can be ordered. Please contact TSM for confirmation before placing an order.
- (2) Redundanted primary measures, acquired by a single logical unit and published on the CANOpen output by one or more PDOs, according to the selected mapping.
- (3) The cable is supplied with all the connector pins crimped on the wires but with the housing to be mounted separately after installation
- (4) MTTFd > 100 years (EN ISO 13849-1) a) b)

■ Screw Magnet "M8, SW13"

■ Magnet 10 x 2 mm■ Screw Magnet "M7, SW11"

3

- a) Standard component. It does not constitute a safety component as defined in the Machinery Directive 2006/42/CE.
- b) Every second failure of an electronic component is regarded as a dangerous failure.
 - The company reserves the right to make any kind of design or functional modification at any moment without prior notice.

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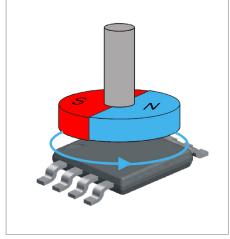
TECHNICAL SPECIFICATION

Rotary measuring range	0 360°
Rotary resolution	Default: 0.01° Selectable: 0.01° - 0.1° - 1°
Rotary linearity (Ta = 25°C)	±0.3°
Rotary temperature drift	±0.01 °/°C typ.
Inclinometer measuring range	Up to ±85° for dual axis type ±180° and 0 360° for single axis type
Inclinometer static accuracy (Ta = 25 °C)	±0.3°
Inclinometer temp. drift (at 0° inclination)	±0.01 °/°C typ.
Working distance*	Axial: 2mm (recommended); air gap 1-4mm Radial: 0mm (recommended); air gap ± 1mm
Material	Housing: PBT + 30%GF Cable sheat: PUR Magnet rotor: see page 8
Protection class	IP67 (acc. to EN 60529)
Temperature range	-40°C +85°C
Size (flange)	Ø 50 mm
Weight approx.	60 g
Shock resistance	acc. to EN 60068-2-27 500 m/s², 11 ms, 100 shocks per axis Axis : X, Y, Z
Vibration resistance	acc. to EN 60068-2-6 10 500 Hz, 100 m/s², 2h per axis Axis : X, Y, Z



Hall effect

Bases its operation principle on the generation of a voltage across an electrical conductor when a magnetic field is applied in a direction perpendicular to the current flow. An hall-effect rotary sensor gives the absolute angular position of a small rotating dipole magnet above the device surface (end of shaft magnet).





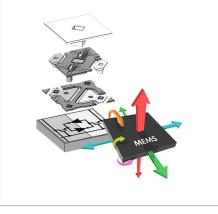
ELECTRICAL CHARACTERISTICS

Power supply range	See order code
Consumption typ.	35 mA (12 VDC, w/o load) 18 mA (24 VDC, w/o load)
Startup time	< 1 s
Interface	See order code
CANopen profile conformity	CiA DS301
EMC compatibility	acc. to EN 61326-1, EN 61326-3-1 (Industrial electromagnetic environment) acc. to EN ISO13766-1, EN ISO13766-2
EU Conformity	EMC directive 2014/30/EU UNECE Reg. 10 R06 RoHS directive 2011/65/EU + 2015/863/EU



MEMS, or Micro Electro-Mechanical System, is a chip-based technology where sensors are composed of proof masses sprung between capacitive plates. Each mass act like a moving plate of a variable capacitor formed by an array of integlaced 'fingers'

interlaced 'fingers'.
When the sensor is tilted, the mass moves changing the distance between the plates and therefore the capacitance. By measuring the capacitance variation the angle value can be detected.



4

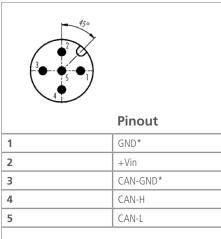
^{*} see magnet position tolerances section

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1] ELECTRICAL CONNECTION M12 X 5 PINS



^{*} GND and CAN_GND terminals are internally connected to each other and identical in their function

4] ELECTRICAL CONNECTION WIRE CONECTOR



^{*} GND and CAN_GND terminals are internally connected to each other and identical in their function

13 & 39] ELECTRICAL CONNECTION DEUTSCH DT04-6P



	Pinout	Colors
1	GND	Blue
2	+Vin	White
3	n.c.	n.c.
4	n.c.	n.c.
5	CAN-L	Brown
6	CAN-H	Black
		-

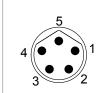
20] ELECTRICAL CONNECTION DEUTSCH DT04-4P



Pinout

1	CAN-L
2	CAN-H
3	+Vin
4	GND

31] ELECTRICAL CONNECTION M8 X 5 PINS



Pinout

	Connector	Accessory
1	CAN-GND*	Brown
2	+Vin	White
3	GND*	Blue
4	CAN H	Black
5	CAN-L	Gray

^{*} GND and CAN_GND terminals are internally connected to each other and identical in their function

30] ELECTRICAL CONNECTION MICROFIT 6 PINS



CONNECTOR SIDE

	Pinout	Colors
1	GND	White
2	+Vin	Blue
3	CAN H	Grey
4	CAN-L	Brown
5	n.c	Black
6	n.c.	n.c

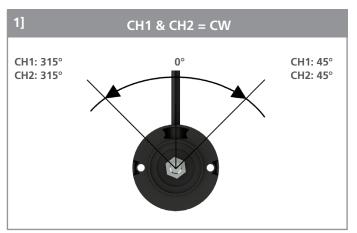
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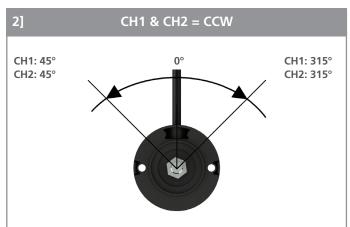
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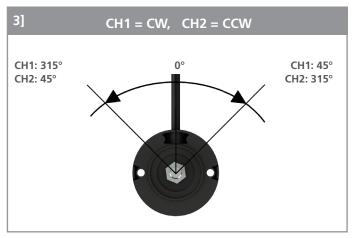


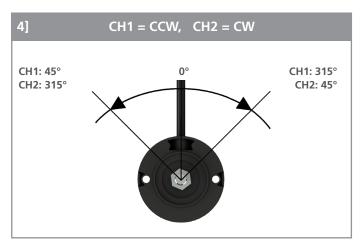


ANGLE COUNTING DIRECTION (BOTTOM VIEW)









"Zero point is not marked and differs for each unit."

It is recommended to set the zero point by sending the related command once the sensor has been installed on the final application"



MAGNET POSITIONING TOLERANCES







a) Any extra offset or misalignment increases the non-linearity.
b) Each sensor MUST be mounted with its own rotor / screw / magnet included in the package.

c) Magnet should NOT be incorporated in a ferromagnetic housing (holder) d) Magnet must NOT be installed in close contact with a surface of ferromagnetic material e) The sensor must be mounted using M4 screws in non-magnetic stainless steel e.g. AISI 316

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INCLINATION COUNTING DIRECTION

Dual axes



RTS100 dual axes inclinometer

The 2-dimensional tilt sensor must be mounted with the base plate in horizontal position, i.e. parallel to the horizontal line. The sensor can be tilted to both the X and Y axes at the same time. A separate measure is provided for each axis.









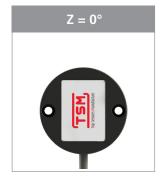
Single axis



RTS100 single axis inclinometer

The 1-dimensional tilt sensor must be installed with the base plate in vertical position, i.e. Z-axis perpendicular to the force of gravity.

The default "zero point" position is the one shown in the following images.







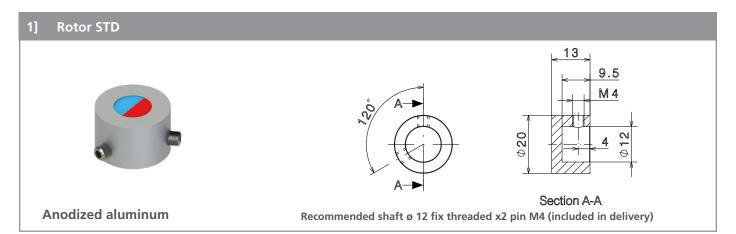


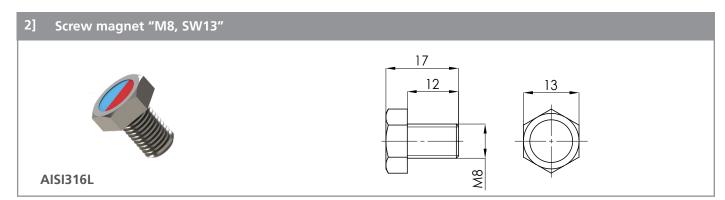
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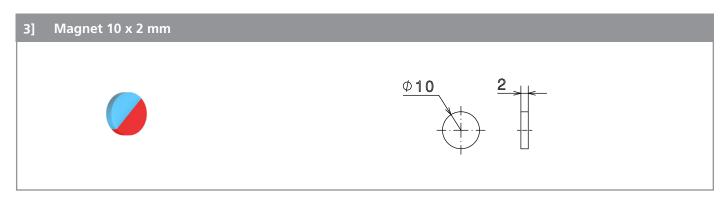
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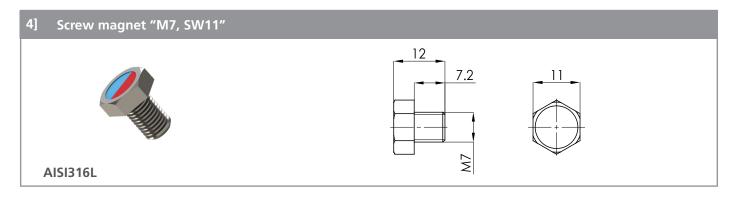










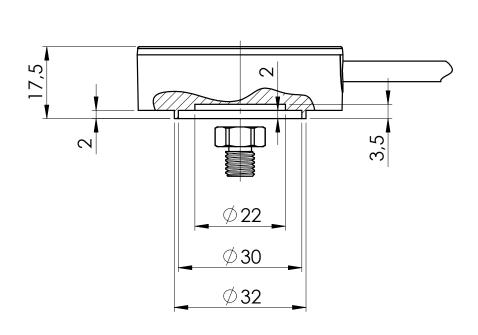


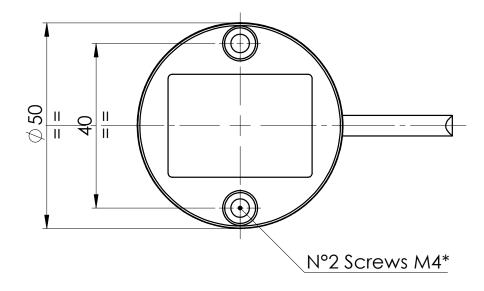
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* MAX tightening torque 2.5Nm