

Preliminary

QG40N-KDXYh-090-AI-K

Inclination sensor
2 axis horizontal

Output
4 - 20 mA

Supply voltage
10 - 30 Vdc

Measuring range
 $\pm 090^\circ$



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Housing
Dimensions
Mounting
Protection
Humidity
Weight
Supply voltage
Polarity protection
Current consumption
Operating temperature
Storage temperature
Measuring range
Center position
Frequency response (-3dB)
Accuracy
Max offset error
Non linearity
Sensitivity error
Resolution at zero
Offset temperature dependency
Max mechanical shock
Output
Output load
Short circuit protection
Response time

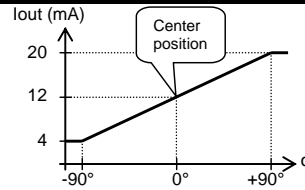
General specifications v20120530

Quadro40: PBTP black
40x40x25 mm
2x steel zinc plated M3x25 mm screws
IP67
0 - 100% RH
ca 45 gr (excl cable)
10 - 30 Vdc
Yes
≤ 30 mA (excluding output signal)
-25 .. +85°C
-25 .. +85°C
$\pm 090^\circ$
Yes, center input to ground
0 - 10 Hz
0,2° (after centering)
$< \pm 0,5^\circ$ over full range
$< 0,1\%$
0,1°
$\pm 0,03^\circ/\text{C}$
10.000g
4 - 20 mA
Rload $\leq 50 \cdot V_s - 300$ (Ω) (Eg: $V_s = 24$ V: Rload ≤ 900 Ω)
Yes (max 10 s)
< 16 ms

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$I_{out} = 12 + 8(\alpha/90)$ [mA]

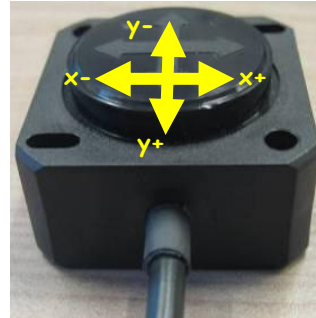
Transfer characteristic



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The default 0° position is when the sensor is mounted horizontally and no acceleration is applied.

Measurement orientation



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Connection

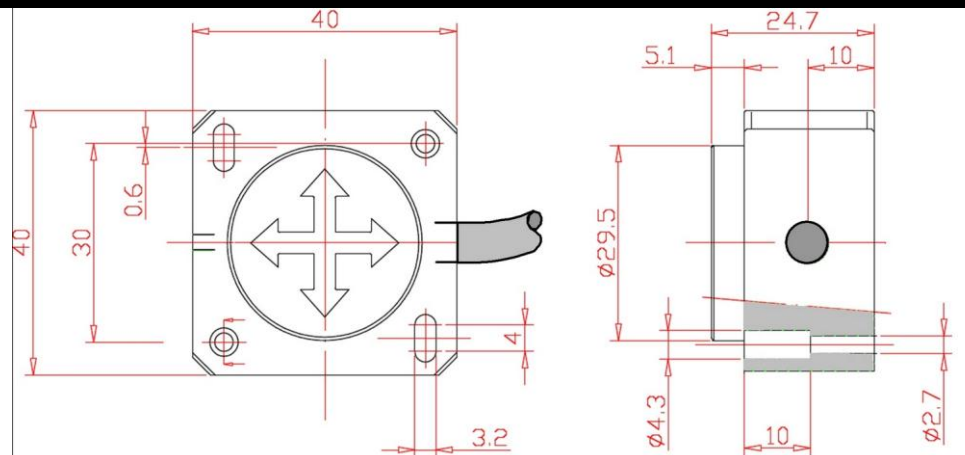
Wire / pin coding

2 m PVC, black \varnothing 6,1 mm, wires: 8x0,25 mm² (static usage)

Brown	+ Supply Voltage
Blue	Gnd
Grey	Output X
White	Center
Red	nc
Green	nc
Yellow	Output Y
Pink	nc

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Mechanical dimensions



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Center function

Centering should be done within 1 min. after power up.
After centering you've 1 min. left for another centering.
Normally the center input should be left unconnected.
Connect center input to ground for more than 0,5s